

## Chapter 3, Exercise 14

Certain sets have geometric properties that guarantee they are simply connected.

- A subset  $\Omega \subset \mathbb{C}$  is **convex** if for any two points in  $\Omega$ , the straight line segment between them is contained in  $\Omega$ . Prove that a convex open set is simply connected.
- More generally, an open set  $\Omega \subset \mathbb{C}$  is **star-shaped** if there exists a point  $z_0 \in \Omega$  such that for any  $z \in \Omega$ , the straight line segment between  $z$  and  $z_0$  is contained in  $\Omega$ . Prove that a star-shaped open set is simply connected. Conclude that the slit plane  $\mathbb{C} - \{(-\infty, 0]\}$  (and more generally any sector, convex or not) is simply connected.
- What are other examples of open sets that are simply connected?

### Solution

#### Part a

First of all, it is clear that  $\Omega$  is path-connected: a path connecting  $x$  and  $y$  in  $\Omega$  is given by the straight line segment connecting  $x$  and  $y$ , which is contained in  $\Omega$  by convexity. Let  $x, y \in \Omega$ , and let  $\gamma_1(t)$  and  $\gamma_2(t)$  be two curves in  $\Omega$  with  $\gamma_1(0) = \gamma_2(0) = x$  and  $\gamma_1(1) = \gamma_2(1) = y$ . Then we can define the homotopy

$$\Gamma(s, t) = s\gamma_2(t) + (1 - s)\gamma_1(t).$$

This is a continuous function of  $s$  and  $t$ , and each point  $\Gamma(s, t)$  lies on the line segment connecting  $\gamma_1(t)$  and  $\gamma_2(t)$ , and is therefore in  $\Omega$  by convexity. Clearly  $\Gamma(s, 0) = x$  and  $\Gamma(s, 1) = y$  for all  $s$ . Thus  $\Gamma$  is a fixed-endpoint homotopy between the curves  $\gamma_1$  and  $\gamma_2$ , and  $\Omega$  is simply connected.

#### Part b

As in part a, it is clear that  $\Omega$  is path-connected: if  $x, y \in \Omega$ , then the concatenation of the straight line segment connecting  $x$  to  $z_0$  and the straight line segment connecting  $z_0$  to  $y$  is contained in  $\Omega$ .

Let  $x \in \Omega$  and let  $\gamma$  be a closed curve with  $\gamma(0) = \gamma(1) = x$ . We need to show that  $\gamma$  can be contracted to a point in  $\Omega$ . Defining

$$\Gamma(s, t) = sz_0 + (1 - s)\gamma(t),$$

we have that  $\Gamma(s, 0) = \Gamma(s, 1)$  for all  $s$ , and so the curve  $\Gamma(s, t)$  remains closed for all  $s$ .  $\Gamma$  is clearly continuous, and  $\Gamma(s, t) \in \Omega$  for all  $s$  and  $t$  by the star-shape of  $\Omega$ . Therefore,  $\Omega$  is simply connected.

It's easy to see that the split complex plane is star-shaped: any point on the real line is a witness. Similarly, any sector of the complex plane is star-shaped, any point lying along the bisector of the sector in  $\Omega$  is a witness.

### Part c

Answers may vary. I did not award points to students who provided a star-shaped region as an example.

## Chapter 8, Exercise 5

Prove that  $f(z) = -\frac{1}{2}(z + 1/z)$  is a conformal map from the half-disc  $\{z = x + iy : |z| < 1, y > 0\}$  to the upper half-plane. [Hint: The equation  $f(z) = w$  has two distinct roots in  $\mathbb{C}$  whenever  $w \neq \pm 1$ . This is certainly the case if  $w \in \mathbb{H}$ .]

### Solution

First, we need to verify that  $f$  maps the half-disc into the upper half-plane. Let  $z$  be a point in the upper half-disc. Then  $z$  has imaginary part bounded above by 1 and  $\frac{1}{z}$  has imaginary part bounded above by  $-1$ . Thus  $z + 1/z$  has negative imaginary part, and  $-\frac{1}{2}(z + \frac{1}{z})$  has positive imaginary part.

Next, we verify that  $f$  is bijective. Suppose that  $f(z) = w$ . Then  $z^2 + 2wz + 1 = 0$  by an easy algebraic calculation. For any fixed  $w$  in the upper half-plane this equation has exactly two distinct complex roots in  $\mathbb{C}$ .

Let  $z_1$  and  $z_2$  be these roots. By Viéta's formulas, we have that  $z_1z_2 = 1$ , and  $z_1 + z_2 = -2w$ . Since  $z_1z_2 = 1$ , we have that either  $z_1$  and  $z_2$  both lie on the unit circle, or exactly one of  $z_1$  and  $z_2$  lies in the open unit disc. But if  $z_1$  lies on the unit disc, then  $z_2 = \bar{z}_1$ , so  $z_1 + z_2$  is real and cannot be equal to  $-2w$  for any  $w$  in the upper half-plane. Thus exactly one of  $z_1$  and  $z_2$  lies in the open unit disc. Without loss of generality assume it is  $z_1$ . Notice that we have that  $z_1$  is the only root of  $z_1 + z_2 = -2w$  that lies in the unit disc, so it immediately follows that  $f(z)$  is an injective function. If we can show that  $z_1$  lies in the upper half of the disc, this will be sufficient to show that  $f$  is surjective.

For this we use  $z_1 + z_2 = -2w$ . If  $z_1$  lies in the lower half of the disc, then  $z_1$  has imaginary part bounded below by  $-1$ , and  $z_2$  has imaginary part bounded below by 1. Thus  $z_1 + z_2$  has positive imaginary part, but  $-2w$  has negative imaginary part. This contradiction establishes that  $z_1$  must not lie in the lower half of the disc. If  $z_1$  lies on the real axis, then  $z_1$  and  $z_2$  are both real, so their sum cannot be  $-2w$ . Thus  $z_1$  lies in the upper half-disc, and  $f(z)$  is bijective.

Finally, we verify that  $f$  is holomorphic in the upper half-disc. But this is clear because the only pole of  $f$  occurs at  $z = 0$ . Thus  $f$  is conformal.

## Chapter 8, Exercise 15

Here are two properties enjoyed by automorphisms of the upper half-plane.

- Suppose  $\Phi$  is an automorphism of  $\mathbb{H}$  that fixes three distinct points on the real axis. Then  $\Phi$  is the identity.

- Suppose  $(x_1, x_2, x_3)$  and  $(y_1, y_2, y_3)$  are two pairs of distinct points on the real axis with  $x_1 < x_2 < x_3$  and  $y_1 < y_2 < y_3$ . Prove that there exists a unique automorphism  $\Phi$  of  $\mathbb{H}$  such that  $\Phi(x_j) = y_j$ ,  $j = 1, 2, 3$ . The same conclusion holds if  $y_3 < y_1 < y_2$  or if  $y_2 < y_3 < y_1$ .

## Solution

### Part a

We know that each automorphism of the upper half-plane is a Möbius transformation of the form

$$f(z) = \frac{az + b}{cz + d}$$

where the matrix

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

can be chosen to have determinant equal to 1. Let  $x_1, x_2, x_3$  be distinct points on the real axis that are fixed by  $\Phi$ . Then the equation  $\Phi(x) = x$  has 3 real solutions. But this equation can be rewritten

$$cx^2 + (d - a)x - b = 0$$

which has at most 2 real solutions unless  $c = b = 0$  and  $d = a$ . Thus  $\Phi$  is the identity automorphism.

### Part b

The cross-ratio

$$\frac{z - z_1}{z - z_3} \frac{z_2 - z_3}{z_2 - z_1}$$

is a Möbius transformation that maps  $z_1$  to 0,  $z_2$  to 1, and  $z_3$  to  $\infty$ . Let  $\Phi_1$  be the cross-ratio for  $x_1, x_2, x_3$  and  $\Phi_2$  be the cross-ratio for  $y_1, y_2, y_3$ . Then

$$\Phi_2^{-1} \circ \Phi_1(z)$$

is a Möbius transformation that maps  $x_1$  to  $y_1$ ,  $x_2$  to  $y_2$ , and  $x_3$  to  $y_3$ . We need to verify that this Möbius transformation maps the upper half-plane to itself.

Evidently this transformation maps the real axis to itself: it is a Möbius transformation so the real axis must map to a line or circle, and 3 points are sufficient to determine a line or circle. Thus the upper half-plane is mapped to either the upper or lower half-plane according to the sign of the determinant of the Möbius transformation. This can be determined through either a direct calculation or common sense: since  $x_1 < x_2 < x_3$ ,  $y_1 < y_2 < y_3$  and Möbius transformations preserve “handedness”, it follows that the upper half-plane maps to the upper half-plane. The same argument works for the case where  $y_2 < y_3 < y_1$  or  $y_3 < y_1 < y_2$ .

The uniqueness of this automorphism follows from part a and a standard group-theoretic argument: if two such automorphisms  $\Phi_1$  and  $\Phi_2$  exist, then  $\Phi_2^{-1} \circ \Phi_1$  is the identity, proving that  $\Phi_1$  and  $\Phi_2$  are the same.